Bilinear Generalized Approximate Message Passing (BiG-AMP) for Dictionary Learning

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Dictionary Learning

Problem objective:

Recover (possibly overcomplete) dictionary $A \in \mathbb{R}^{M \times N}$ and sparse matrix $X \in \mathbb{R}^{N \times L}$ from (possibly noise-corrupted) observations Y = AX + W.

Possible generalizations:

- non-additive corruption (e.g., one-bit or phaseless Y)
- incomplete/missing observations
- structured sparsity
- non-negative A and X, or simplex-constrained

Contributions

- We propose a unified approach to these dictionary-learning problems that leverages the recent framework of approximate message passing (AMP).
- While previous AMP algorithms have been proposed for the linear model:
 - Infer $\mathbf{x} \sim \prod_n p_{\mathbf{x}}(x_n)$ from $\mathbf{y} = \mathbf{\Phi}\mathbf{x} + \mathbf{w}$ with AWGN \mathbf{w} and known $\mathbf{\Phi}$.

[Donoho/Maleki/Montanari'10]

- or the generalized linear model:
 - Infer $\mathbf{x} \sim \prod_n p_{\mathbf{x}}(x_n)$ from $\mathbf{y} \sim \prod_m p_{\mathbf{y}|\mathbf{z}}(y_m|z_m)$ with hidden $\mathbf{z} = \mathbf{\Phi}\mathbf{x}$ and known $\mathbf{\Phi}$. [Rangan'10]
- our work tackles the generalized *bilinear* model:
 - Infer $\mathbf{A} \sim \prod_{m,n} p_{\mathbf{a}}(a_{mn})$ and $\mathbf{X} \sim \prod_{n,l} p_{\mathbf{x}}(x_{nl})$ from $\mathbf{Y} \sim \prod_{m,l} p_{\mathbf{y}|\mathbf{z}}(y_{ml}|z_{ml})$ with hidden $\mathbf{Z} = \mathbf{A}\mathbf{X}$. [Schniter/Cevher'11]
- In addition, we propose methods to select the rank of *Z*, to estimate the parameters of *p*_a, *p*_x, *p*_{y|z}, and to handle non-separable priors on *A*, *X*, *Y*|*Z*.

Description

Bilinear Generalized AMP (BiG-AMP)



- In AMP, beliefs are propagated on a loopy factor graph using approximations that exploit certain blessings of dimensionality:
 - **1** Gaussian message approximation (motivated by central limit theorem),
 - 2 Taylor-series approximation of message differences.
- Rigorous analyses of GAMP for CS (with large iid sub-Gaussian Φ) reveal a state evolution whose fixed points are optimal when unique. [Javanmard/Montanari'12]

Adaptive Damping

- The heuristics used to derive BiG-AMP hold in the large system limit: $M, N, L \to \infty$ with $\frac{M}{N} \to \delta$ and $\frac{M}{L} \to \gamma$ for constants $\delta, \gamma \in (0, 1)$.
- In practice, M, N, L are finite and the rank N is often very small!
- \blacksquare To prevent divergence, we damp the updates using an adjustable parameter $\beta \in (0,1].$
- Moreover, we adapt β by monitoring (an approximation to) the cost function minimized by BiG-AMP and adjusting β as needed to ensure decreasing cost.

$$\begin{split} \hat{J}(t) &= \sum_{n,l} D\Big(\hat{p}_{\mathsf{x}_{nl}|\mathbf{Y}} \big(\cdot \mid \mathbf{Y} \big) \Big\| \, p_{\mathsf{x}_{nl}}(\cdot) \Big) &\leftarrow \mathsf{KL} \text{ divergence between posterior } \& \text{ prior} \\ &+ \sum_{m,n} D\Big(\hat{p}_{\mathsf{a}_{mn}|\mathbf{Y}} \big(\cdot \mid \mathbf{Y} \big) \Big\| \, p_{\mathsf{a}_{mn}}(\cdot) \Big) \\ &- \sum_{m,l} \mathrm{E}_{\mathcal{N}(\mathsf{z}_{ml}; \bar{p}_{ml}(t); \nu_{ml}^{p}(t))} \, \big\{ \log p_{\mathsf{y}_{ml}|\mathsf{z}_{ml}}(y_{ml} \mid \mathsf{z}_{ml}) \big\}. \end{split}$$

Parameter Tuning via EM

- AMP methods assume $p_x, p_a, p_{y|z}$ are known, which is rarely true in practice.
- We assume families for these priors (e.g., Gaussian mixture) and estimate the associated parameters θ using expectation-maximization (EM), as done for GAMP in [Vila/Schniter'13].

Taking X, A, and Z to be the hidden variables, the EM recursion becomes

$$\begin{aligned} \hat{\boldsymbol{\theta}}^{k+1} &= \arg\max_{\boldsymbol{\theta}} \mathbb{E}\left\{ \log p_{\boldsymbol{X},\boldsymbol{A},\boldsymbol{Z},\boldsymbol{Y}}(\boldsymbol{X},\boldsymbol{A},\boldsymbol{Z},\boldsymbol{Y};\boldsymbol{\theta}) \,\middle|\, \boldsymbol{Y}; \hat{\boldsymbol{\theta}}^{k} \right\} \\ &= \arg\max_{\boldsymbol{\theta}} \left\{ \sum_{n,l} \mathbb{E}\left\{ \log p_{\mathsf{x}_{nl}}(\mathsf{x}_{nl};\boldsymbol{\theta}) \,\middle|\, \boldsymbol{Y}; \hat{\boldsymbol{\theta}}^{k} \right\} \\ &+ \sum_{m,n} \mathbb{E}\left\{ \log p_{\mathsf{a}_{mn}}(\mathsf{a}_{mn};\boldsymbol{\theta}) \,\middle|\, \boldsymbol{Y}; \hat{\boldsymbol{\theta}}^{k} \right\} \\ &+ \sum_{m,l} \mathbb{E}\left\{ \log p_{\mathsf{y}_{ml}|\mathsf{z}_{ml}}(y_{ml} \,|\, \mathsf{z}_{ml}; \boldsymbol{\theta}) \,\middle|\, \boldsymbol{Y}; \hat{\boldsymbol{\theta}}^{k} \right\} \end{aligned}$$

• For tractability, the θ -maximization is performed one variable at a time.

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Numerical Results for Dictionary Learning

We compared against several state-of-the-art techniques

- K-SVD [Aharon/Elad/Bruckstein'06]
 - the standard; a generalization of K-means clustering
- SPAMS [Mairal/Bach/Ponce/Sapiro'10]
 - a highly optimized online approach
- ER-SpUD [Spielman/Wang/Wright'12]
 - the recent breakthrough on provable square-dictionary recovery

to our proposed technique:

- EM-BiG-AMP
 - BiG-AMP under AWGN, \mathcal{BG} signal, and EM-adjusted λ, μ_x, v_x, v_w .

Square Dictionary Recovery: Phase Transitions

Mean NMSE over 10 realizations for recovery of an $N \times N$ dictionary from $L\!=\!5N\log N$ examples with sparsity $K\!:$



Noiseless case: EM-BiG-AMP's phase transition curve is much better than that of K-SVD and SPAMS and almost as good as ER-SpUD(proj)'s.
 Noisy case: EM-BiG-AMP is robust to noise, while ER-SpUD(proj) is not.

Square Dictionary Recovery: Runtime to NMSE=-60 dB



EM-BiG-AMP runs within a factor-of-5 from the fastest approach (SPAMS).
 EM-BiG-AMP runs orders-of-magnitude faster than ER-SpUD(proj).

Overcomplete Dictionary Recovery: Phase Transitions

Mean NMSE over 10 realizations for recovery of an $M \times (2M)$ dictionary from $L = 5N \log N$ examples with sparsity K:



Noiseless case: EM-BiG-AMP's phase transition curve is much better than that of K-SVD and SPAMS. Note: ER-SpUD not applicable when M ≠ N.
 Noisy case: EM-BiG-AMP is again robust to noise.

Application: Hyperspectral Unmixing

- In Hyperspectral unmixing, a sensor captures M wavelengths per pixel, over a scene of L pixels comprised of N materials.
- The received HSI data Y is modeled as

$$\boldsymbol{Y} = \boldsymbol{A}\boldsymbol{X} + \boldsymbol{W} \in \mathbb{R}^{M imes L}_+,$$

where the *n*th column of $A \in \mathbb{R}^{M \times N}_+$ is the spectrum of the *n*th material, the *l*th column of $X \in \mathbb{R}^{N \times L}_+$ describes the abundance of materials at the *l*th pixel (and thus must sum to one), and W is additive noise.

- The goal is to jointly estimate A and X.
 - Standard NMF-based unmixing algs (e.g., VCA [Nascimento'05], FSNMF [Gillis'12]) assume pure-pixels, which may not occur in practice.
 - Furthermore, they do *not* exploit spectral coherence, spatial coherence, and sparsity, which do occur in practice.
 - Recent Bayesian approaches to unmixing (e.g., SCU [Mittelman'12]) exploit spatial coherence using Dirichlet processes, albeit at very high complexity.



EM-BiG-AMP for HSI Unmixing

- To enforce non-negativity we place non-negative Gaussian Mixture (NNGM) prior on a_{mn}, and to encourage sparsity a Bernoulli-NNGM prior on x_{nl}.
 - We then use EM to learn the (B)NNGM parameters.
- To enforce the sum-to-one constraint on each column of X, we augment both
 Y and A with a row of random variables with mean one and variance zero.
- To exploit spectral coherence we employ a hidden Gauss-Markov chain across each column in *A*, and to exploit spatial coherence we employ an Ising model to capture the support across each row in *X*.
 - We use EM to learn the Gauss-Markov and Ising parameters.



EM-BiG-AMP for HSI Unmixing



- Inference on the bilinear sub-graph is tackled using the BiG-AMP algorithm.
- Inference on the Gauss-Markov and Ising subgraphs are tackled using standard soft-input/soft-output belief propagation methods.
- Messages are exchanged between the three sub-graphs according to the sum-product algorithm, akin to "turbo" decoding in modern communication receivers [Schniter'10].

Numerical Results: Pure-Pixel Synthetic Data

- Pure pixel abundance maps X of size $L = 50 \times 50$ were generated with N = 5 materials residing in equal-sized spatial strips.
- Endmember spectra *A* were taken from a reflectance library.
- AWGN observations with SNR = 30 dB.
- Averaging performance over 10 realizations

		Runtime	NMSES	NMSEA
	EM-BiG-AMP	5.57 sec	- 57.4 dB	-108.6 dB
	VCA + FCLS	4.13 sec	-39.6 dB	-30.5 dB
ſ	FSNMF + FCLS	3.97 sec	-25.3 dB	-12.5 dB
	SCU	2808 sec	-30.6 dB	-20.5 dB

EM-BiG-AMP gives significantly better NMSE than competing algorithms.

• EM-BiG-AMP's gives runtime comparable to the fastest algorithms and 3 orders-of-magnitude faster than SCU.





Results: SHARE 2012 dataset



RGB image from the SHARE 2012 dataset.

- Experiment constructed to provide pure pixels.
- EM-BiG-AMP yields the purest abundances (right).
- EM-BiG-AMP yields the best spectral angles (below).
- EM-BiG-AMP's runtime is on par with the fastest algorithm, FSNMF+FCLS.

(a) EM-BiG-AMP (runtime = 2.26 sec):



(b) VCA+FCLS (runtime = 2.60 sec):



(b) FSNMF+FCLS (runtime = 1.76 sec):









(c) SCU (runtime = 1885 sec):



N = 4 material abundance maps.

	grass	dry sand	white TyVek	black felt
EM-BiG–AMP	0.999	0.999	1.000	0.998
VCA + FCLS	0.999	0.999	0.999	0.981
FSNMF + FCLS	0.999	0.997	1.000	0.977
SCU	0.999	0.999	0.999	0.859

Spectral Angle Distance (SAD) between recovered and ground truth endmembers.

Conclusion

- BiG-AMP = approximate message passing for the generalized bilinear model.
- A novel approach to matrix completion, robust PCA, dictionary learning, etc.
- Includes mechanisms for adaptive damping, parameter tuning, non-separable priors, and model-order selection.
- Competitive with state-of-the-art algorithms for each application.
 - Best phase transitions for MC, RPCA, overcomplete DL.
 - Runtimes not far from the fastest algorithms.
- Currently working on generalizations of BiG-AMP to parametric models (e.g., Toeplitz matrices), as well as various applications.

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